

## DAFTAR PUSTAKA

- A, S. (2016, April 18). Terrasolid User Guides. Retrieved from Terrasolid Web site.:  
Retrieved from [http://www.terrasolid.com/download/tscan .pdf](http://www.terrasolid.com/download/tscan.pdf)
- Aditya, S. (2019). TINJAUAN KEHANDALAN CITRA LIDAR UNTUK PENGUKURAN TITIK-TITIK TINGGI TANAH ( Studi Kasus: Desa Bukit Indah, Kecamatan Tanjung Selor, Kabupaten Bulungan - Kalimantan Timur ). Skripsi thesis. Retrieved from <http://eprints.itn.ac.id/1625/>
- Ageng, Yoedo (2013).Registrasi Point Cloud Objek Berkontur Menggunakan Metode Red Green Blue Color Iterative Closest Point. JAVA Journal of Electrical and Electronics Engineering. Volume 11, Number 2, October 2013
- Aoki, Y., Goforth, H., Srivatsan, R. A., & Lucey, S. (2019). Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), 7163-7172 .
- Arun, Somani; Thomas S. Huang; Steven D. Blostein (1987). "Least-square fitting of two 3-D point sets". IEEE Pattern Analysis and Machine Intelligence. 9 (5): 698–700. doi:10.1109/TPAMI.1987.4767965. PMID 21869429.
- Ayman, F. ( 2009). Strip Adjustment Procedure To Mitigate The Impact Of Inaccurate Mounting Parameters In Parallel Lidar Strips. The Remote Sensing and Photogrammetry Society and Blackwell Publishing Ltd.
- Bergevin, R., Soucy, M., Gagnon, H., & Laurendeau, D. (1996). Towards a general multi-view registration technique. IEEE Transactions on Pattern Analysis and Machine Intelligence, 18(5):540 - 547. doi:10.1109/34.494643
- Bani, Alief. 2019. Analisis Nilai Lahan di Kecamatan Depok Kabupaten Sleman Menggunakan Sistem Informasi Geografis. Yogyakarta. Universitas Muhammadiyah Surakarta.
- Besl, P. J., & McKay, N. D. (1992, April). Method for registration of 3-D shapes. IEEE Transactions on Pattern Analysis and Machine Intelligence, 1611, 568-606. Retrieved from <https://www.spiedigitallibrary.org/conference-proceedings-of-spie/1611/1/Method-for-registration-of-3-D-shapes/10.1117/12.57955.short?SSO=1>
- Chen , Z., Li , J., & Yang, B. (2012). A Strip Adjustment Method of UAV-Borne LiDAR Point Cloud. ACRS 2012. Can Tho city, Viet Nam: AARS. Retrieved from [https://a-a-r-s.org/proceeding/ACRS2012/Proceeding%20ACRS%202012/Poster%20Session/PS2%20\(1-14\)%20Algorithm/PS2-8.pdf](https://a-a-r-s.org/proceeding/ACRS2012/Proceeding%20ACRS%202012/Poster%20Session/PS2%20(1-14)%20Algorithm/PS2-8.pdf)
- Chen, X., Jin, Z., Wang, Q., Yang, W., Qingming Liao, & Hongying Meng. (2022). Unsupervised visual feature learning based on similarity guidance. Neurocomputing. Retrieved from <https://doi.org/10.1016/j.neucom.2021.11.102>
- Chen, Y., & Medioni, G. (1992). Object modelling by registration of multiple range images. 145-155. Retrieved from <https://www.sciencedirect.com/science/article/abs/pii/026288569290066C>
- Chena, H.-P., Changb, K.-T., & Liu, J.-K. (2012). STRIPE ADJUSTMENT OF AIRBORNE LIDAR DATA USING GROUND. ACRS2012. Taiwan:

Minghsin University of Science and Technology.

- Choy, C., Dong, W., & Koltun, V. (2020). Deep Global Registration. Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), 2514-2523. Retrieved from [https://openaccess.thecvf.com/content\\_CVPR\\_2020/html/Choy\\_Deep\\_Global\\_Registration\\_CVPR\\_2020\\_paper.html](https://openaccess.thecvf.com/content_CVPR_2020/html/Choy_Deep_Global_Registration_CVPR_2020_paper.html)
- Favre, K., Pressigout, M., Marchand, E., & Morin, L. (2021). Plane-based Accurate Registration of Real-world Point Clouds. IEEE International Conference on Systems, Man, and Cybernetics (SMC), 2018-2023. doi:10.1109/SMC52423.2021.9658727
- Gökgöz, T., & M. Baker, M. K. (2015). Large Scale Landform Mapping Using Lidar DEM. ISPRS International Journal of Geo-Information, 1336-1345.
- Huang, X., Mei, G., & Zhang, J. (2020). Feature-Metric Registration: A Fast Semi-Supervised Approach for Robust Point Cloud Registration Without Correspondences. Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), 11366-11374. Retrieved from [https://openaccess.thecvf.com/content\\_CVPR\\_2020/html/Huang\\_Feature-Metric\\_Registration\\_A\\_Fast\\_Semi-Supervised\\_Approach\\_for\\_Robust\\_Point\\_Cloud\\_CVPR\\_2020\\_paper.html](https://openaccess.thecvf.com/content_CVPR_2020/html/Huang_Feature-Metric_Registration_A_Fast_Semi-Supervised_Approach_for_Robust_Point_Cloud_CVPR_2020_paper.html)
- Huang, X., Mei, G., Zhang, J., & Abbas, R. (2021). A comprehensive survey on point cloud registration. arXiv preprint arXiv. doi:2103.02690
- Islam, M. M., & Sultana, N. (2018). Comparative Study on Machine Learning Algorithms for Sentiment Classification. International Journal of Computer Applications, 182(21). doi:10.5120/ijca2018917961
- Kager. (2004). Discrepancies between overlapping laser scanner strips— simultaneous fitting of aerial laser scanner strips. International Archives of the Photogrammetry, Remote Sensing and Spatial Information Sciences, 35(B1): 555–560.
- Kandia, P. (2012). Pembentukan Model dan Parameter untuk Estimasi Kelapa Sawit Menggunakan Data Light Detection and Ranging (LiDAR). Jurusan Teknik Geodesi dan Geomatika.
- Li, Z., Tan, J., & Liu, H. (2019). Rigorous Boresight Self-Calibration of Mobile and Remote Sensing, 11(4), 442. Retrieved from <http://dx.doi.org/10.3390/rs11040442>
- Liu, Y., Bi, J.-W., & Fan, Z.-P. (2017). Multi-class sentiment classification: The experimental comparisons of feature selection and machine learning algorithms. Expert Systems with Applications, 80(3). doi:10.1016/j.eswa.2017.03.042
- Liu, Y., Bi, J.-W., & Fan, Z.-P. (2017). Multi-class sentiment classification: The experimental comparisons of feature selection and machine learning algorithms. (Expert Systems With Applications ), pp. 323-339. doi:10.1016/j.eswa.2017.03.042
- Luo, X. (2021). Efficient English text classification using selected Machine Learning Techniques. Alexandria Engineering Journal, 3401–3409. Retrieved from <https://doi.org/10.1016/j.aej.2021.02.009>
- Park, S. Y., & Subbarao, M. (2003, December). An accurate and fast point-to-plane registration technique. Pattern Recognition Letters, 24, 2967-2976.

- doi:[https://doi.org/10.1016/S0167-8655\(03\)00157-0](https://doi.org/10.1016/S0167-8655(03)00157-0)
- Rusinkiewicz, S and Marc Levoy. Efficient Variants of the ICP Algorithm. Proceedings of the International Conference on 3-D Digital Imaging and Modeling (3DIM), pp. 145–152, 2001.
- Saputra, A. C., Sitepu, A. B., Stanley, Sigit, P. W., Tetuko, P. G., & Nugroho, G. C. (Maret 2019). The Classification of the Movie Genre based on Synopsis of the Indonesian Film. International Conference of Artificial Intelligence and Information Technology (ICAIIIT), 201-204. doi:10.1109/ICAIIIT.2019.8834606
- Soininen. (2015, October 9). Terrasolid User Guides. Retrieved from <http://www.terrasolid.com/download/tmatch.pdf>
- Viana, Nadya; Nadya ,Ledy; Susatio,Eko (2019). SISTEM PENGENALAN WAJAH 3D MENGGUNAKAN ICP DAN SVM. Vol. 6, No. 6, Desember 2019
- Vosselman, G. (2000). Slope based filtering of laser altimetry data. International archives of photogrammetry and remote sensing, 33(B3/2; PART 3), 935-942.
- W. Kornus, & A. Ruiz. (2013). STRIP ADJUSTMENT OF LIDAR DATA. ISPRS.
- Wang, Y., & Solomon, J. M. (2019). Deep Closest Point: Learning Representations for Point Cloud Registration. 3523-3532. Retrieved from [https://openaccess.thecvf.com/content\\_ICCV\\_2019/html/Wang\\_Deep\\_Closest\\_Point\\_Learning\\_Representations\\_for\\_Point\\_Cloud\\_Registration\\_ICCV\\_2019\\_paper.html](https://openaccess.thecvf.com/content_ICCV_2019/html/Wang_Deep_Closest_Point_Learning_Representations_for_Point_Cloud_Registration_ICCV_2019_paper.html)
- Wehr, A., & b, U. L. (1999). Airborne laser scanning—an introduction and overview. ISPRS Journal of photogrammetry and remote sensing, 54, 68-82. doi:[https://doi.org/10.1016/S0924-2716\(99\)00011-8](https://doi.org/10.1016/S0924-2716(99)00011-8)
- Zhang, J., Yao, Y., & Deng, B. (2020, December 29). Fast and Robust Iterative Closest Point. IEEE Transactions on Pattern Analysis and Machine Intelligence. Retrieved from <https://arxiv.org/abs/2007.07627>
- Zhang, Zhengyou (1994). "Iterative point matching for registration of free-form curves and surfaces". International Journal of Computer Vision. 13 (12): 119–152. CiteSeerX 10.1.1.175.770. doi:10.1007/BF01427149.